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<u>Am</u>	Technische Universität Hamburg-Harburg Institut für Numerische Simulation
TUHH > Institut für Numerische Simulation > GAMM 2008	
Home Registration	Welcome to the GAMM Workshop
Program	Applied and Numerical Linear Algebra
Abstracts	with special emphasis on
Participants	Regularization of Ill-posed Problems
How to find us Accommodation	····g·····
Organizers	Date:
Supported by	September 11-12, 2008 Technische Universität Hamburg-Harburg, Germany
Bundesministerium für	
Bildung und Forschung GAMM	Invited speakers (confirmed):
	Lars Eldén (Linköping, Sweden)
History	Per Christian Hansen (Lyngby, Denmark)
Harrachov 2007	Marielba Rojas (Lyngby, Denmark)
Dusseldorf 2006	Fiorella Sgallari (Bologna,Italy)
Dresden 2005 Hagen 2004	
Braunschweig 2003	
Bielefeld 2002	
Berlin 2001	
last modified on: 2008-04-14,	14.45

Quasi-Minimal Residual Eigenpairs

Jens-Peter M. Zemke zemke@tu-harburg.de

Institut für Numerische Simulation Technische Universität Hamburg-Harburg

> 10.09.2008 9.50 am – 10.15 am

IWASEP 7 June 9-12, 2008 Dubrovnik, Croatia

Abstract Krylov methods Krylov decompositions

QMR for eigenpairs

QMR eigenpairs SVD-based characterization Grassmannian characterization

Examples & Pictures

Graphics guide An example

Conclusion and Outview

We consider a given Krylov decomposition

$$AQ_k = Q_{k+1}\underline{C}_k = Q_kC_k + q_{k+1}c_{k+1,k}e_k^T.$$

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We suppose that

$$A \in \mathbb{C}^{(n,n)}$$

$$egin{aligned} Q_{k+1} &= egin{pmatrix} Q_k & q_{k+1} \end{pmatrix} \in \mathbb{C}^{(n,k+1)} \ \underline{C}_k &= egin{pmatrix} C_k \ c_{k+1,k} e_k^T \end{pmatrix} \in \mathbb{C}^{(k+1,k)} \end{aligned}$$

is a matrix of basis vectors,

is unreduced extended Hessenberg.

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 $A \in \mathbb{C}^{(n,n)}$ is a general square matrix,

$$egin{aligned} Q_{k+1} &= ig(Q_k \quad q_{k+1} ig) \in \mathbb{C}^{(n,k+1)} \ & \underline{C}_k &= ig(egin{aligned} C_k \ C_{k+1,k} e_k^T ig) \in \mathbb{C}^{(k+1,k)} & ext{ is un} \end{aligned}$$

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We do not consider perturbations. We remark that important parts of the results carry over to general rectangular approximations \underline{C}_k of *A* which not necessarily have to be Hessenberg.

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We proceed similar to the QMR approach often applied to linear systems,

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Definition (QMR eigenpair)

The pair $(\dot{\theta}, \dot{y} = Q_k \dot{v})$ is a QMR eigenpair, iff

$$\frac{(\dot{\theta}I_k - \underline{C}_k)\dot{v}\|}{\|\dot{v}\|} = \min_{z \in \mathbb{C}, v \in \mathbb{C}^k, \|v\| = 1} \frac{\|(z\underline{I}_k - \underline{C}_k)v\|}{\|v\|},$$
(3)

where "min loc" denotes a (not necessarily strict) local minimum.

We denote the SVD of ${}^{z}\underline{C}_{k} \equiv z\underline{I}_{k} - \underline{C}_{k}$ by $U(z)\Sigma(z)V(z)^{H} = U\Sigma(z)V^{H}$.

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$$\sigma_k(z) = \|\sigma_k(z)u_k\| = \frac{\|z\underline{C}_kv_k\|}{\|v_k\|} = \min_{v} \frac{\|z\underline{C}_kv\|}{\|v\|},$$

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QMR eigenpairs: SVD steepest descent

Simple singular values $\sigma(z)$ and corresponding singular vectors v_k , u_k of the complex matrices ${}^{z}\underline{C}_{k} = z\underline{I}_{k} - \underline{C}_{k}$ are real analytic (Sun, 1988),

$$\sigma(z+w) = \sigma(z) + \sigma_z(z)w + \sigma_{\overline{z}}(z)\overline{w} + O(|w|^2)$$
(6)

$$= \sigma(z) + 2\Re((u_k^H \underline{I}_k v_k)w) + O(|w|^2).$$
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We obtain steepest descent by subtracting the conjugate of the gradient $\sigma_z(z)$:

$$z_{\text{new}} = z - \alpha \, \overline{u_k^H I_k v_k} = z - \alpha \, v_k^H \underline{I}_k^H u_k \tag{8}$$

$$= z - \frac{\alpha}{\sigma_k} v_k^H \underline{I}_k^H (z \underline{I}_k - \underline{C}_k) v_k = z - \frac{\alpha}{\sigma_k} v_k^H (z I_k - C_k) v_k.$$
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We note that $\sigma_k(z)$ is the backward error of the approximate eigenvalue *z*. Setting $\alpha = \sigma_k$ yields alternating projections and is nearly optimal:

$$z_{\text{new}} = v_k^H C_k v_k. \tag{10}$$

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Enhancement: Damped Newton's method or simply BFGS.

Remark: Multiple singular values can not occur in the symmetric case due to the unreduced Hessenberg structure, but still may be pathologically close, compare with results by Lehmann and Wilkinson.



QMR eigenpairs: Grassmannian Optimization

Given an QMR eigenvector \dot{v} , we obtain $\dot{\theta}$ by the Rayleigh quotient with C_k , as

$$\dot{\theta} = \frac{\dot{v}^H C_k \dot{v}}{\dot{v}^H \dot{v}} = \operatorname*{arg\,min}_{z \in \mathbb{C}} \frac{\|(z\underline{I}_k - \underline{C}_k)\dot{v}\|}{\|\dot{v}\|}.$$
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ruhh

Jens-Peter M. Zemke

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It can then be shown that the QMR eigenvectors give minima of the resulting real-analytic function

$$\lambda : G_1(\mathbb{C}^k) \to \mathbb{R}_{\geq 0},$$

$$\lambda : v \mapsto \lambda(v) = \frac{\|(z(v)\underline{I}_k - \underline{C}_k)v\|^2}{\|v\|^2} = \frac{v^H(\underline{C}_k)^H\underline{C}_kv}{v^Hv} - \left|\frac{v^HC_kv}{v^Hv}\right|^2.$$
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The stationary points of real-analytic λ are always singular vectors.

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We experimented with steepest descent and Newton's method for minimization of (the real-analytic) λ on the first (complex) Grassmannian in the framework of optimization on Riemannian manifolds (as recently developed by Smith; Edelman, Arias & Smith; Manton).

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For Newton's method we have to compute the second covariant derivative, i.e., to use the Levi-Civita connection on the Grassmannian. This is simplified if using orthonormal frames, compare with the introductory textbook by Boothby.

QMR eigenpairs: Grassmannian Newton

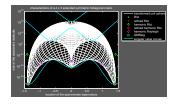
```
for j = 1:convergence
```

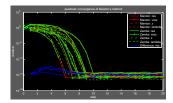
```
[Q,R] = qr(v); W = Q(:,2:k); v = Q(:,1);
```

```
z = v'*Ck*v; zuCk = z*uIk-uCk;
zuCkW = zuCk*W; zuCkv = zuCk*v;
slambda = norm(zuCkv);
y = zuCkW'*zuCkv;
grad = 2*[real(y);imag(y)];
res = norm(grad);
```

```
A = zuCkW' zuCkW; zCk = uIk'*zuCk;
g1 = (zCk*W)'*v; r1 = real(g1); c1 = imag(g1);
g2 = W'*(zCk*v); r2 = real(g2); c2 = imag(g2);
outer1 = [r1+r2;c1+c2];
messe = 2*(real(A) imag(A)';...
imag(A) real(A)]-...
2*slambda^2xI-...
2*outer1*outer1'-2*outer2*outer2';
ab = Hesse\grad;
u = -W*(ab(1:k-1)+i*ab(k:2*k-2));
normu = norm(u);
v = v*cos(normu)+u*sin(normu)/normu;
```

(This is to convince you that the code is short enough to fit on one page.)





end

'UHH

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The norm of the residual of $(\tilde{\theta}, \tilde{y})$ gives the backward error, i.e.,

$$w = \min\left\{\|\Delta A\| : (A + \Delta A)\tilde{y} = \tilde{y}\,\tilde{\theta}\right\}.$$
(15)

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$$w = \min\left\{\|\Delta A\| : (A + \Delta A)\tilde{y} = \tilde{y}\,\tilde{\theta}\right\}.$$
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Remark 1: Without additional knowledge a small backward error is the best we can achieve.

We associate with every real or complex approximate eigenpair ($\tilde{\theta}, \tilde{y} = Q_k \tilde{y}$) a point (z, w) in the plane $\mathbb{R} \times \mathbb{R}$ or $\mathbb{C} \times \mathbb{R}$:

$$z = \tilde{\theta}, \qquad w = \frac{\|(\tilde{\theta}\underline{I}_k - \underline{C}_k)\tilde{v}\|}{\|\tilde{v}\|}.$$
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Remark 1: Without additional knowledge a small backward error is the best we can achieve.

Remark 2: There exist "graphical" bounds for general and "Rayleigh" approximations.

1 0

A beautiful example

As an example we use

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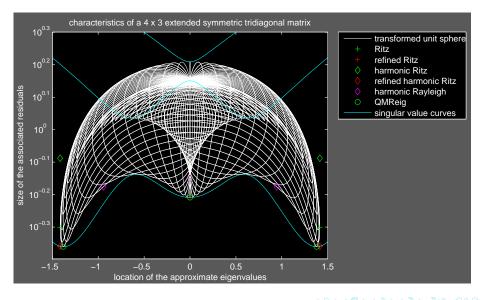
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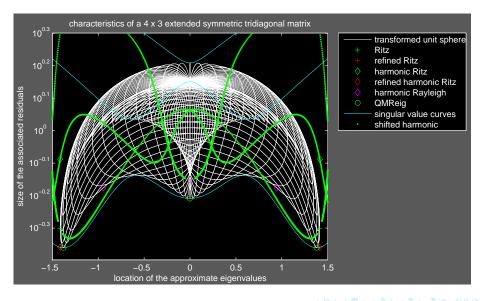
$$\dot{\theta}_{1,3} = \mp \frac{\sqrt{2}}{16} \sqrt{113 + 2\Re \sqrt[3]{y}} \approx \mp 1.37898323557, \quad \dot{\theta}_2 = 0.$$
⁽²⁰⁾

A beautiful example



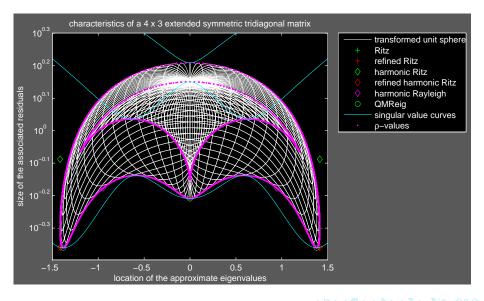
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- Is there an "algebraic" characterization of all QMR eigenvalues?

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There are cases of infinitely many QMR eigenpairs, namely, QMR eigenvalues on a circle, the zeros of $z\overline{z} - c^2 = 0$. Mostly, we obtain slightly less than *k* QMR eigenvalues. We need to know the number of zeros of a real algebraic variety.

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Thank you for your attention!

Appendix Loss of QMR eig

A warning: loss of QMR eigenvalues; academic

An academic example is

$$\underline{C}_k = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix}.$$

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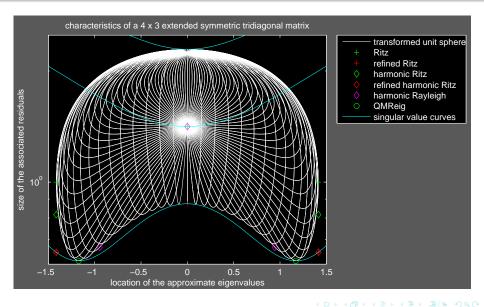
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At zero a stationary point exists which is a maximum of the smallest singular value curve and a saddle point of the transformed sphere.

Appendix Loss of QMR ei

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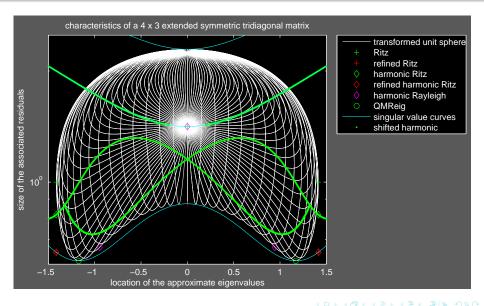
Jens-Peter M. Zemke

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Quasi-Minimal Residual Eigenpairs

Appendix Loss of QMR e

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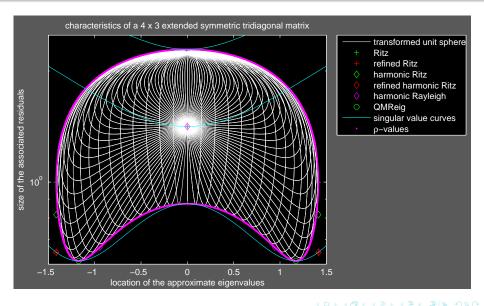
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Appendix Loss of QMR eigenvalue

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An interesting example is extended symmetric and generated using MATLAB's randn and hess functions and is approximately given by

$$\underline{C}_k \approx \begin{pmatrix} 0.46204801 & 1.75649255 & 0\\ 1.75649255 & 0.23525002 & -0.70301190\\ 0 & -0.70301190 & 1.90702012\\ 0 & 0 & 1.21958322 \end{pmatrix}.$$



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The computed Ritz, harmonic Ritz and ρ -values all differ. There are only two QMR eigenvalues. The smallest of all these and the norms of the eigenpair residuals (denoted by $n(\cdot, \cdot)$) are approximately given by

$$\theta_1 \approx -1.490413407713866,$$

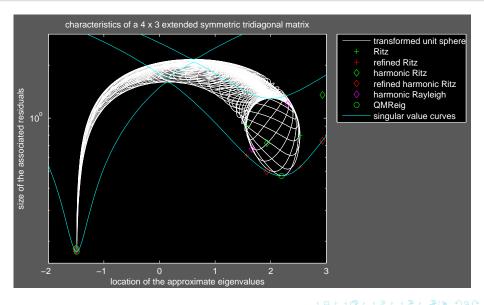
 $\theta_1 \approx -1.509143602001304,$
 $\rho_1 \approx -1.487425797938723,$
 $\dot{\theta}_1 \approx -1.489367749116040.$

$$\begin{split} n(\theta_1, \nu_1) &\approx 0.1854320889556417, \\ n(\underline{\theta}_1, \underline{\nu}_1) &\approx 0.1810394571648995, \\ n(\rho_1, \underline{\nu}_1) &\approx 0.1797320840508472, \\ n(\dot{\theta}_1, \dot{\nu}_1) &\approx 0.1746583392656590. \end{split}$$

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Appendix Loss of QMR eige

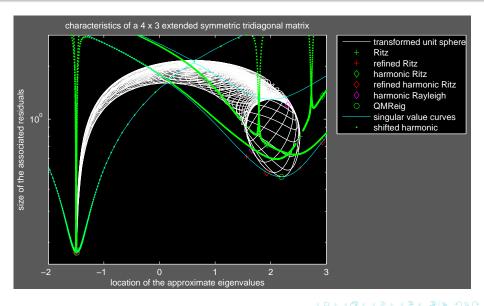
The 'random' example



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Appendix Loss of QMR eig

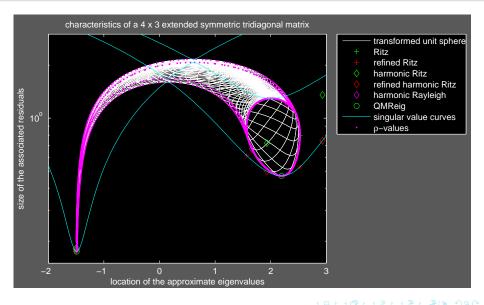
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The QMR eigenvectors are harmonic Ritz vectors, the shifts are given by

$$\tau_{\pm} = \dot{\theta} \pm \sigma_k(\dot{\theta}), \tag{24}$$

in accordance with Lehmann's results for the symmetric case, see also van den Eshof's doctoral thesis (2003).

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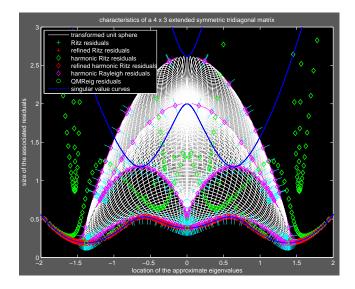
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Shifted harmonic Ritz values and the SVD

The harmonic Ritz values $\underline{\theta}$ are the eigenvalues of the inverse of a section of the pseudoinverse,

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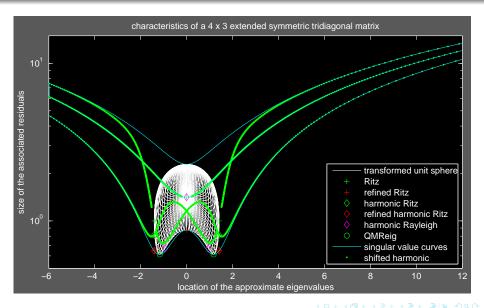
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As the harmonic Ritz values are not shift-invariant (in contrast to Ritz and QMR eigenvalues), and by interlacing of singular values and the connection of the pseudoinverse to the singular value decomposition we might expect to see relations between shifted harmonic Ritz and the SVD in the pictures.

Appendix Harmonic Ritz

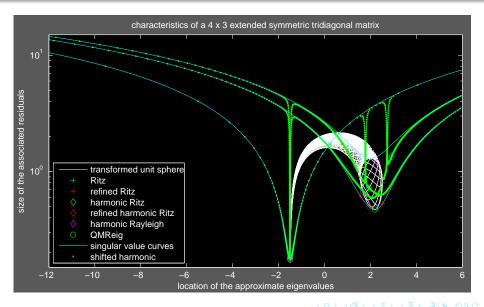
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Appendix An extended Jord

A Jordan block: infinitely many QMR eigenvalues

A startling example used already by Eising in context of the distance to uncontrollability (given in terms of the the best QMR eigenpair) is

$$\underline{C}_4 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}.$$

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The residual of the corresponding QMR eigenpairs is given by

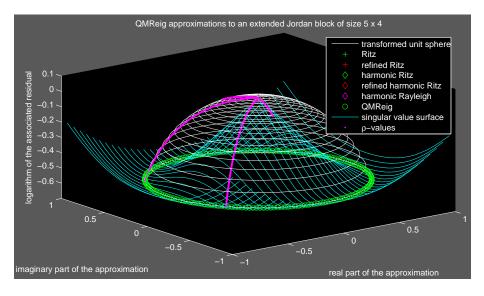
$$\|(\dot{\theta}_{\phi}\underline{I}_{k} - \underline{C}_{k})\dot{s}_{\phi}\| = \sin\left(\frac{\pi}{k+1}\right) \quad \forall \ \phi.$$
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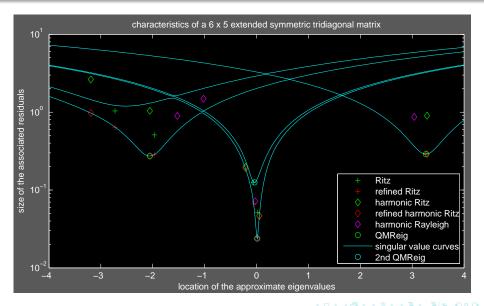
A Jordan block: infinitely many QMR eigenvalues



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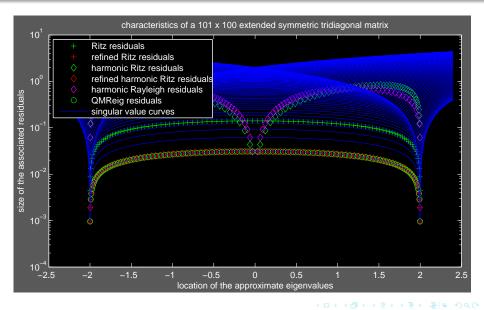
Appendix "Local optimality" is indeed a local prope

Always remember: It's only locally optimal ...



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Large matrices and harmonic Ritz



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He was interested in generalizing his results [Seite 246, 1963]:

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"Für Aufgaben mit komplexen Eigenwerten stehen viele der Untersuchungen allerdings noch aus. Mit diesen Problemen befaßt sich eine in Arbeit befindliche Dissertation."

We have extended his approach to general complex square matrices by replacing "Lehmann optimality" by "backward error". Thus, we have extended his work to normal matrices (Q_{k+1} orthonormal; Arnoldi's method).

Lehmann used the information included in $Q \in \mathbb{C}^{(n,k)}$ and $W = AQ \in \mathbb{C}^{(n,k)}$, where $A \in \mathbb{C}^{(n,n)}$ is selfadjoint. We used a generic $x = Qv \in \mathbb{C}^n$.

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Lehmann imposed the least-squares optimality conditions [(5a), 1963]

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Lehmann was interested in optimal shifts, i.e., shifts *z* resulting in a minimal radius $\sigma(z)$ of the inclusion. These are [Satz 4, 1963] among the stationary points of $\sigma^2(z)$,

$$\frac{\partial \sigma^2(z)}{\partial z} = 0.$$

Lehmann's little-known results

Differentiating an expression involving the Temple quotient $T_{\tau}(x)$, he obtained the shifted harmonic Ritz values [(20a)+(28), 1963] of Morgan (1991) and Freund (1992),

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He (defined and) noted certain interesting symmetries/properties, namely

$$\begin{aligned} \tau &= z \mp \sigma(z), & \underline{\theta}(\tau) = z \pm \sigma(z), & [(\text{Seite 251}), 1963] \\ \underline{\theta}(\tau) &= T_{\tau}(\underline{x}), & T_{\tau}(\underline{x}) = \frac{\underline{x}^{H}(A - \tau I)^{H}(A - \tau I)\underline{x}}{\underline{x}^{H}(A - \tau I)^{H}\underline{x}} + \tau, & [(15), 1963] \\ 2z &= \tau + \underline{\theta}(\tau), & z^{2} - \sigma^{2}(z) = \tau \cdot \underline{\theta}(\tau). & [(8b)+(21), 1963] \end{aligned}$$

The function λ is stationary only for singular vectors for $z = v^H C_k v$. If the corresponding singular value is simple, we have found a stationary point on the corresponding singular value surface.

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The Hessean has negative eigenvalues whenever the singular value $\sigma_j(z)$ found is not a smallest one, since in forming the Hesse matrix we subtract a positive semidefinite symmetric matrix (of rank less equal two) from the realification of

$$A(z) = W^H(^{z}\underline{C}_k^{Hz}\underline{C}_k - \sigma_j(z)^2 I_k)W, \qquad W = v_j^{\perp}.$$

The Hermitean matrix A(z) has the eigenvalues $\sigma_i^2 - \sigma_j^2$, $i \neq j$. The smallest eigenvalue of the Hesse matrix is bounded from above by Weyl's Lemma by $\lambda_{\min} \leq \sigma_{\min}^2 - \sigma_j^2 < 0$.

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Is every QMR eigenpair obtained through SVD minimization also obtained by Grassmannian optimization with SPD Hessean and vice versa? How to prove this?

1

One direction is quite simple: As any QMR eigenpair $(\dot{\theta}, \dot{v})$ from the SVD minimization satisfies

$$\hat{\theta} = \frac{\hat{v}^H C_k \hat{v}}{\hat{v}^H \hat{v}} = z(\hat{v}),$$

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There can be no smaller function value nearby, since this would result in a sequence of $v(\epsilon_i)$, $||v(\epsilon_i)|| = 1$, arbitrarily close to $v = \dot{v}$, ||v|| = 1, with

$$\sigma_k(z(v)) = \|(z(v)\underline{I}_k - \underline{C}_k)v\| > \|(z(v(\epsilon_i))\underline{I}_k - \underline{C}_k)v(\epsilon_i)\| \ge \sigma_k(z(v(\epsilon_i))),$$

thus, there would be a sequence $z_i = z(v(\epsilon_i)) \rightarrow z = \dot{\theta}$ with

$$\sigma_k(\dot{ heta}) > \sigma_k(z_i),$$

which gives with the continuity of the functions involved a contradiction.

If the singular vector to the smallest singular values as a function of the parameter ϵ is continuous, which is at least the case if the singular value is simple and thus real analytic by Sun's results, we can prove that a minimum of the vector-valued function is indeed also a minimum of the singular value surface.

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Denote the "smallest" singular vector of $(z+\epsilon)C_k$ by $v(\epsilon) = v_k(z+\epsilon)$, i.e.,

$$((z+\epsilon)\underline{I}_k-\underline{C}_k)\nu(\epsilon)=u_k(z+\epsilon)\sigma_k(z+\epsilon),$$

and define

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Then, obviously,

$$\sigma_k^2(z+\epsilon) \ge \|^{z(\epsilon)} \underline{C}_k v(\epsilon)\|_2^2 \ge \sigma_k^2(z(\epsilon)).$$
(28)



We now use the "closeness" of the functions σ_k^2 and λ , i.e.,

$$\sigma_k^2(z+\epsilon) \ge \lambda(\nu(\epsilon)) = \|^{z(\epsilon)} \underline{C}_k \nu(\epsilon)\|_2^2 \ge \sigma_k^2(z(\epsilon)).$$
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Suppose that we do not have a minimum at z, i.e., let N_z denote a neighborhood of z,

$$\forall N_z \quad \exists w \in N_z : \sigma_k(w) < \sigma_k(z), \tag{30}$$

or, by the Axiom of Choice, a sequence of points $\{\epsilon_i \in \mathbb{C}\}_{i=1}^\infty$ such that

$$\lim_{i\to\infty}\epsilon_i=0 \quad \text{and} \quad \sigma_k(z+\epsilon_i)<\sigma_k(z) \quad \forall i\in\mathbb{N}. \tag{31}$$

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This gives a contradiction.

It can be shown that the shifted harmonic Ritz values $\underline{\theta}$, the shift ("target") τ and the resulting ρ -values are related.

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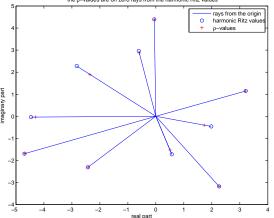
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i.e., both $\underline{\theta}_j$ and ρ_j are on the same ray originating from zero and on the same side.



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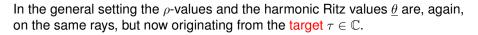
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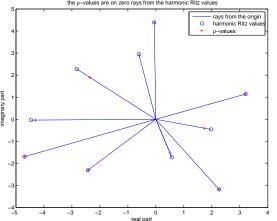
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